

Fig.1

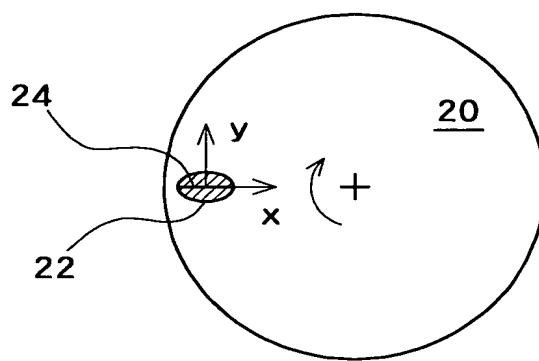


Fig.2

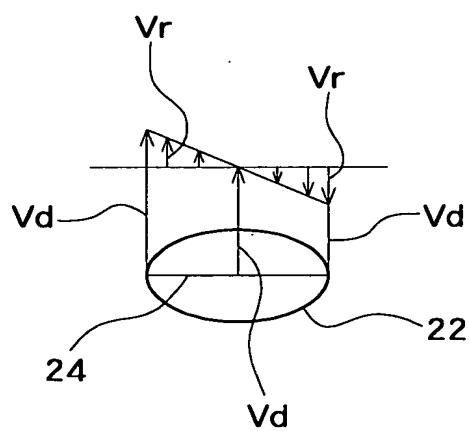


Fig.3

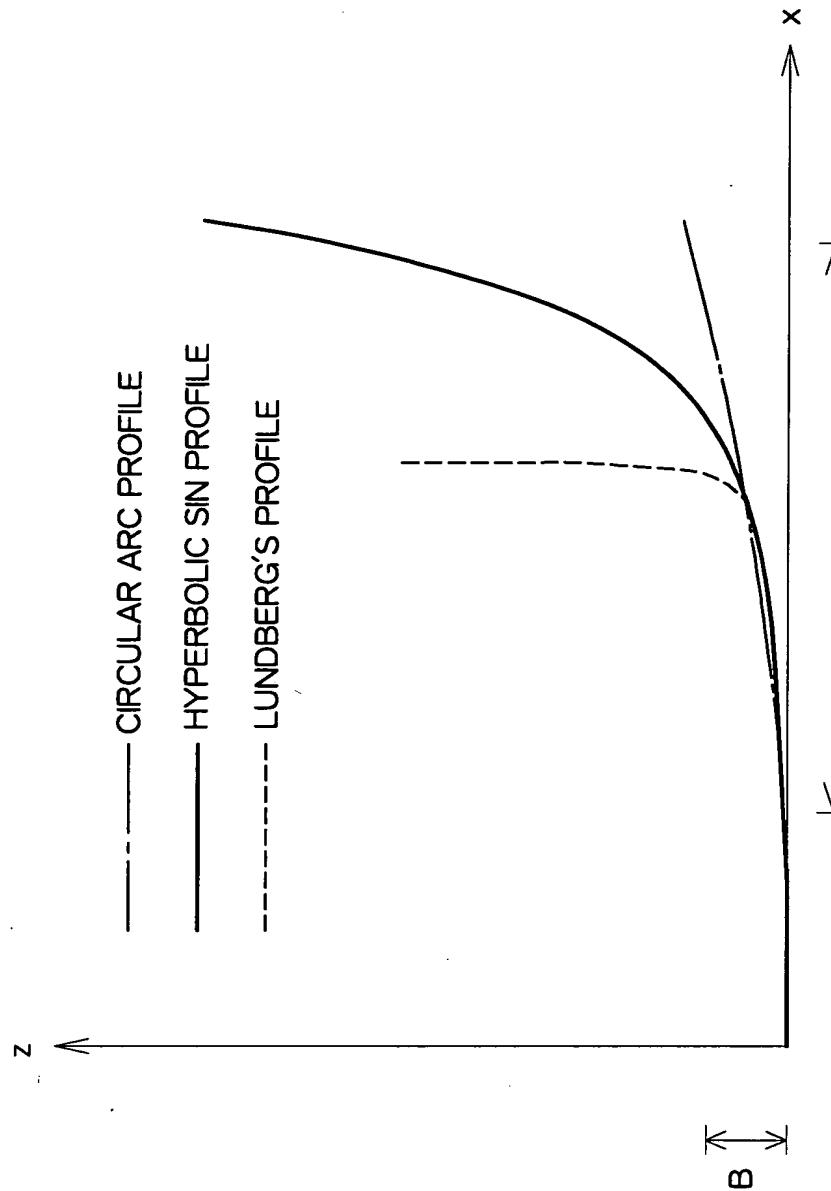


Fig.4

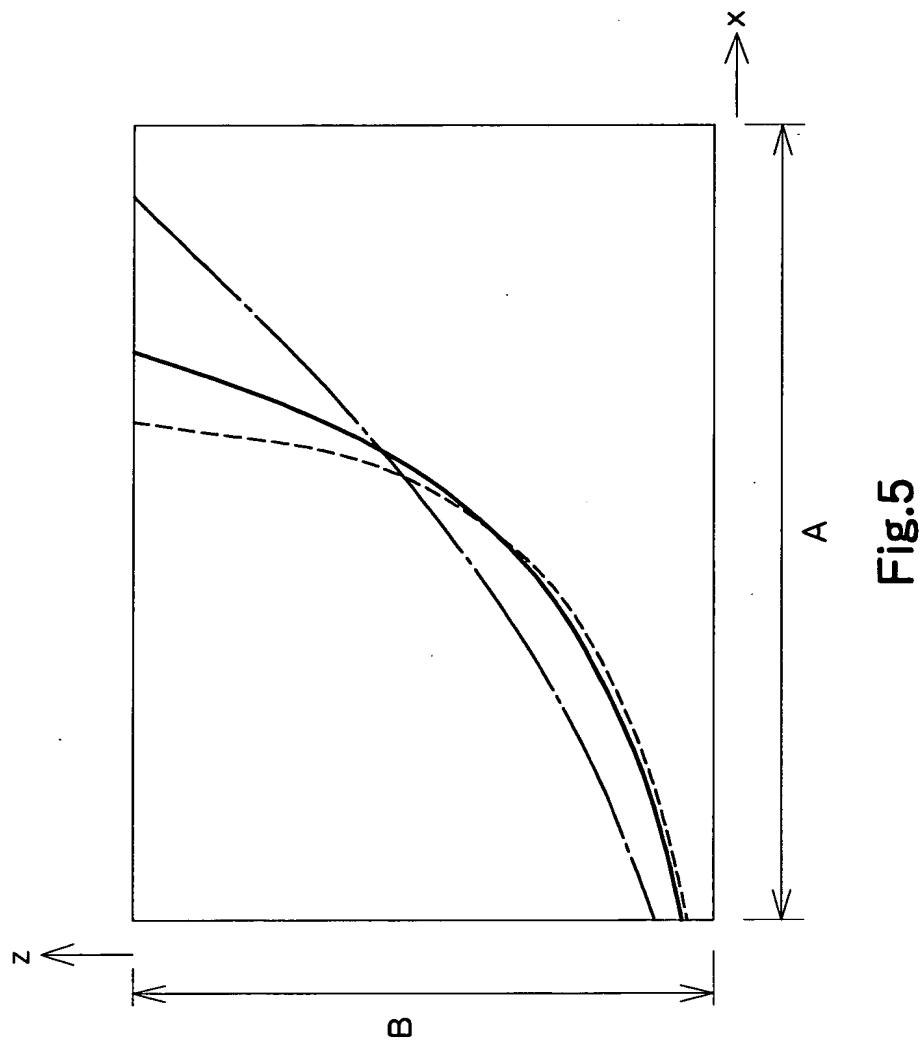


Fig. 5

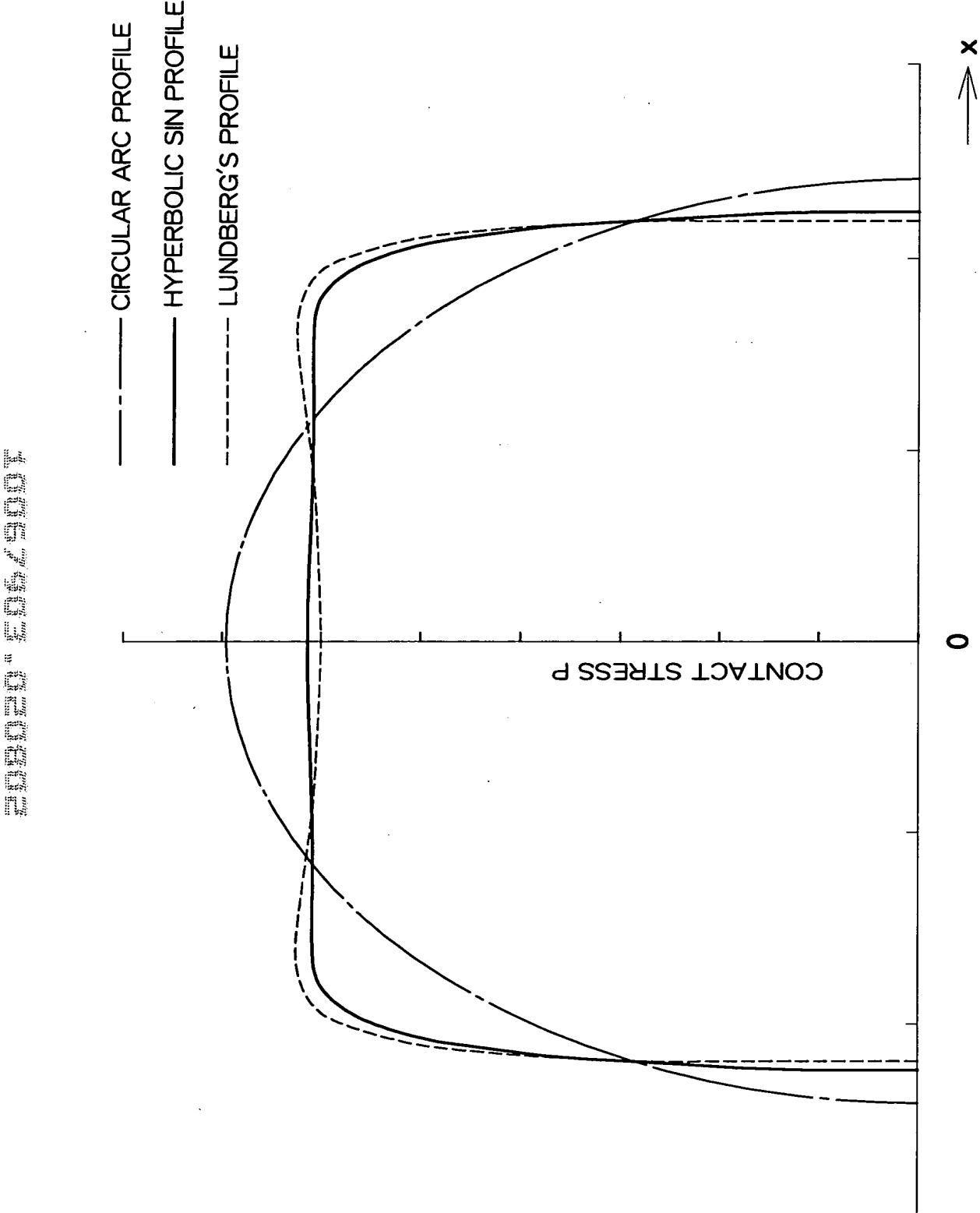


Fig. 6

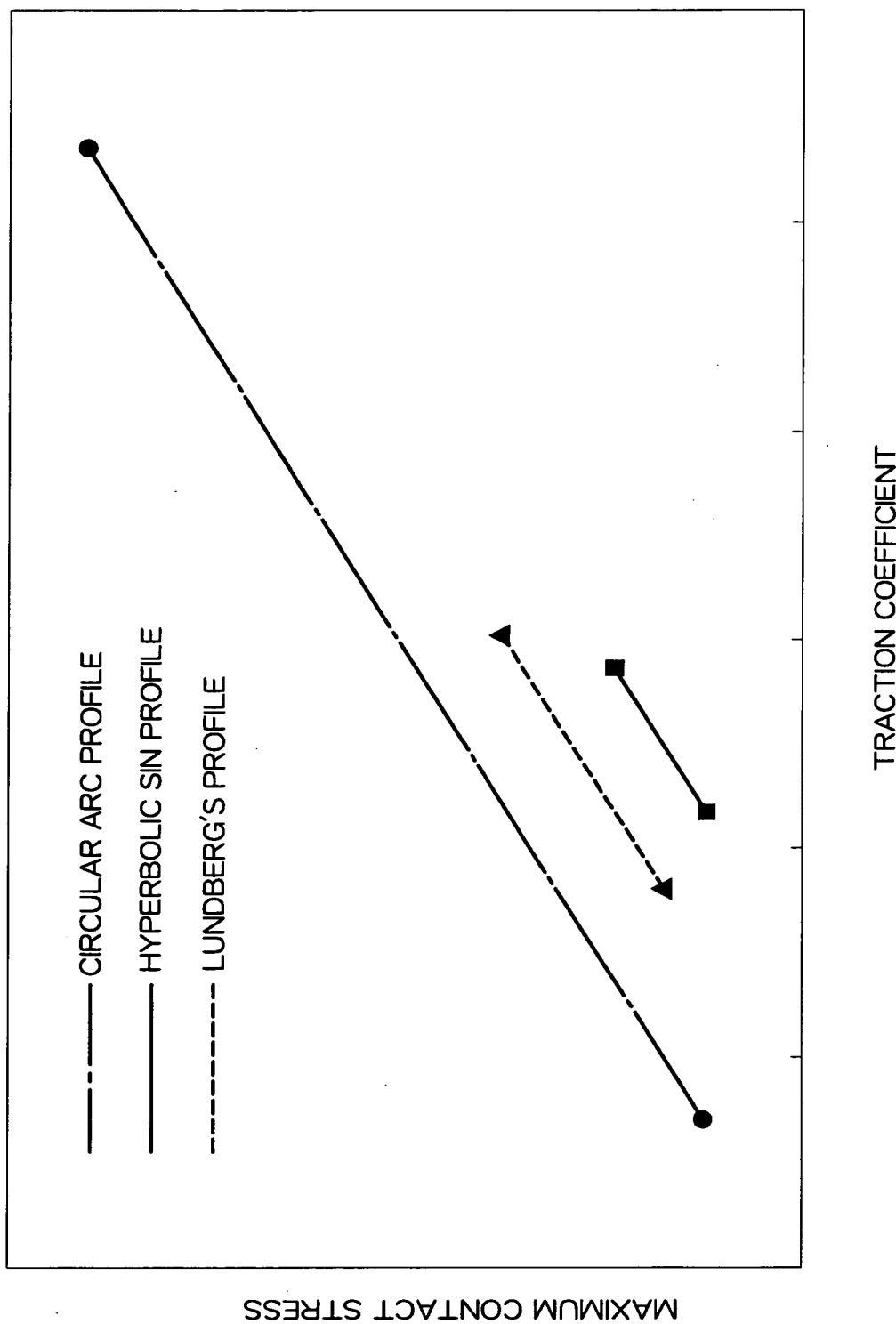


Fig. 7

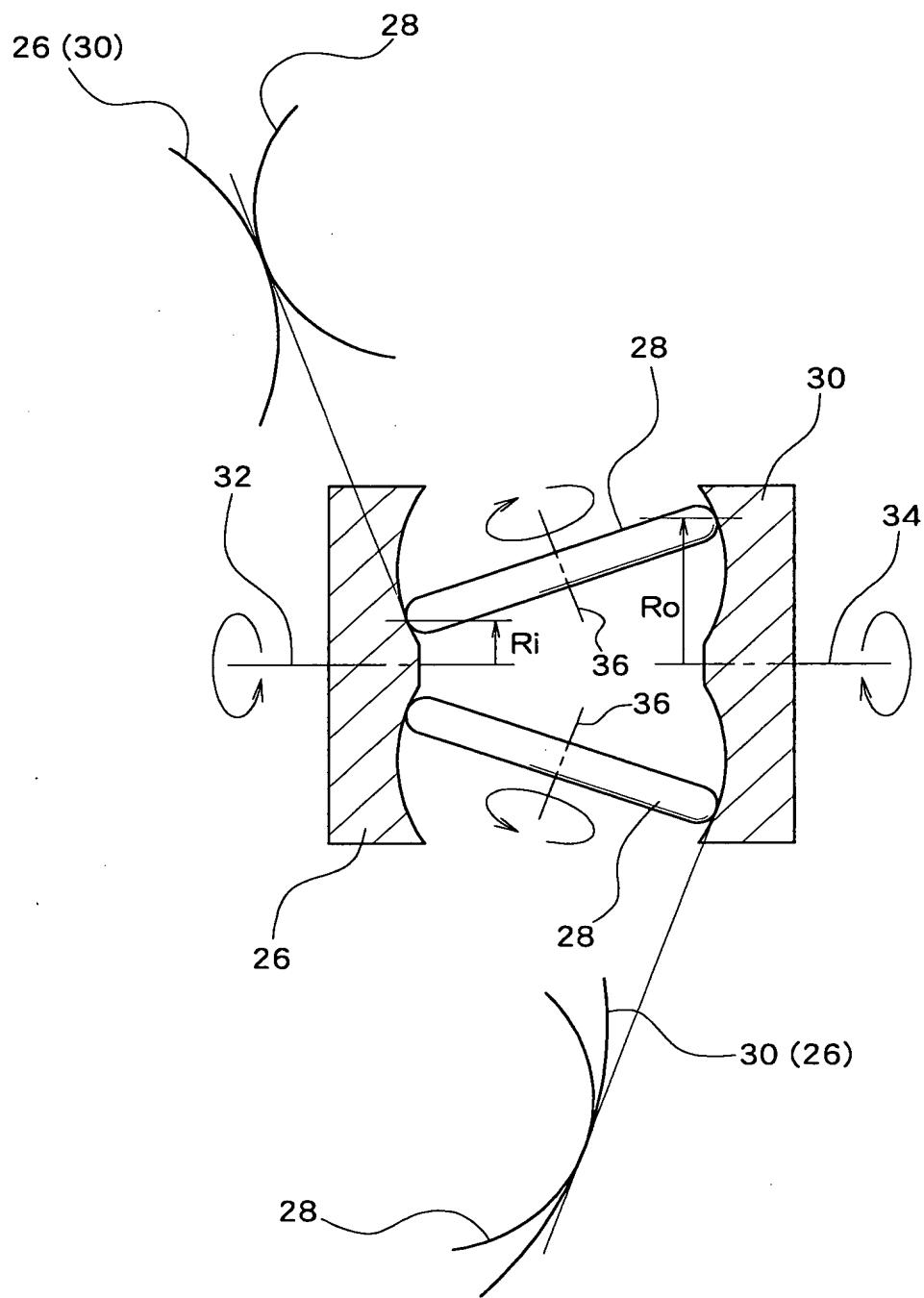


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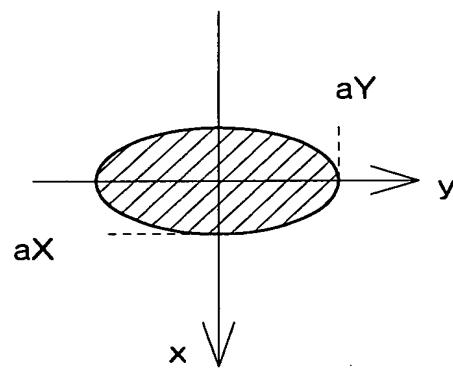


Fig.9

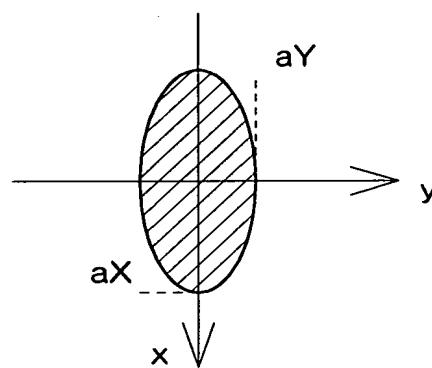


Fig.10

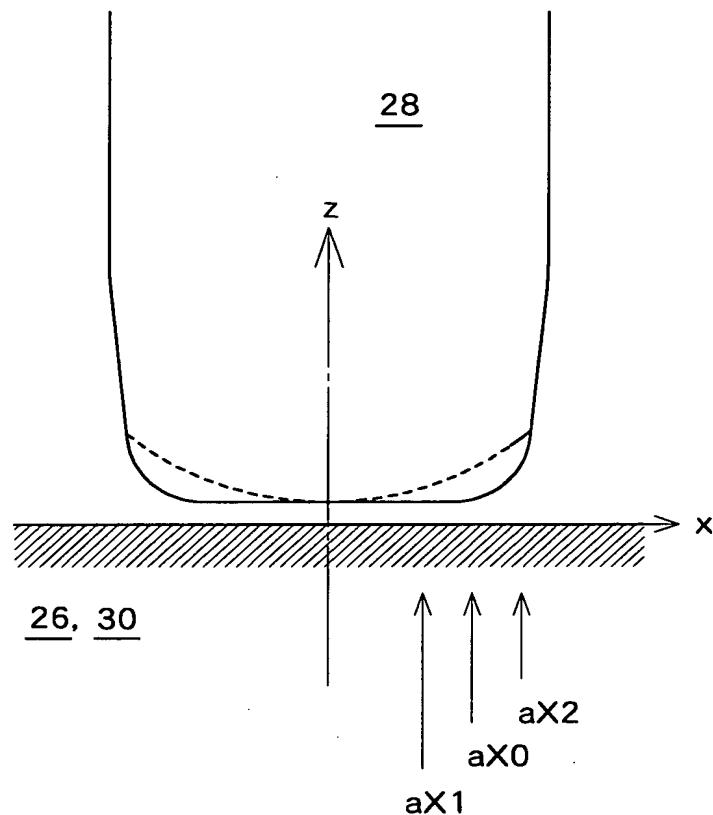


Fig. 11

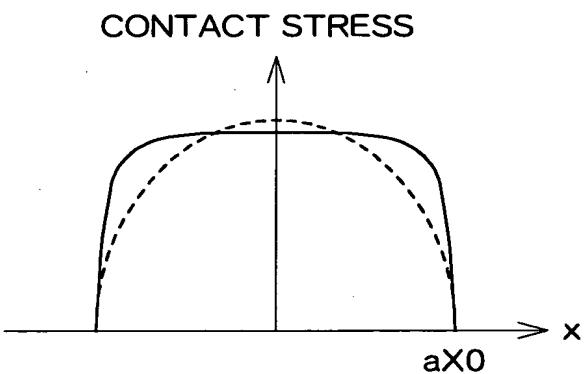


Fig.12

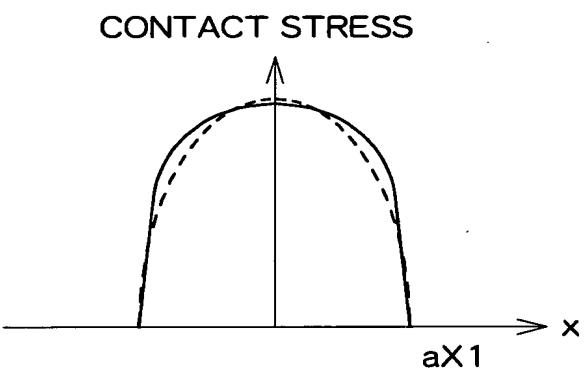


Fig.13

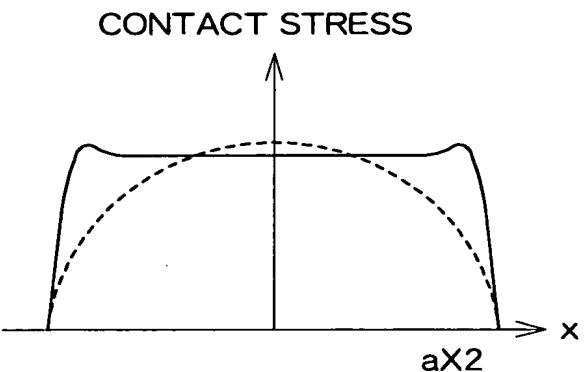
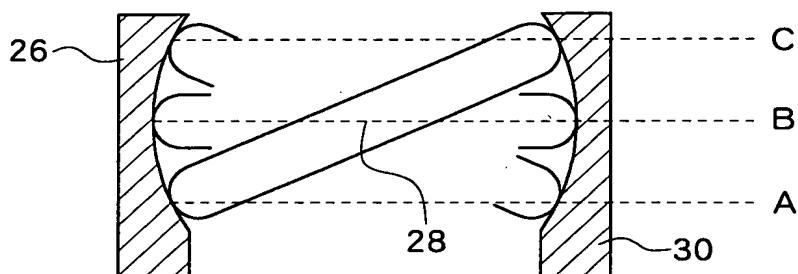


Fig.14



SPEED CHANGING STATE	INPUT CONTACT	OUTPUT CONTACT
DECELERATION	A	C
CONSISTENT SPEED	B	B
ACCELERATION	C	A

Fig. 15

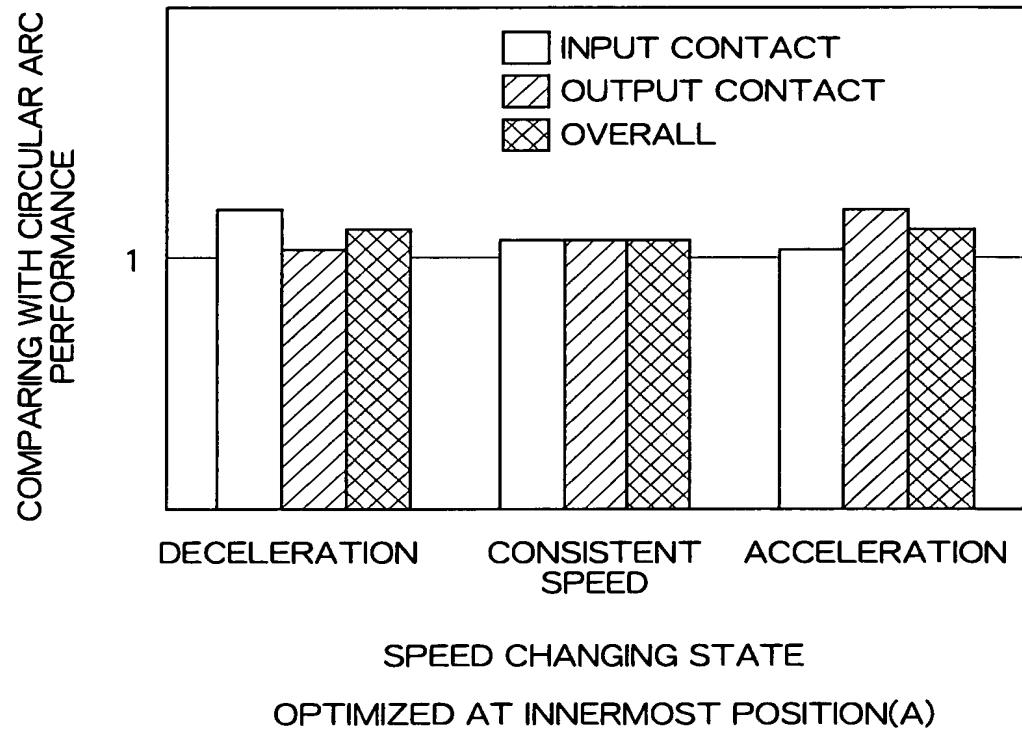


Fig. 16

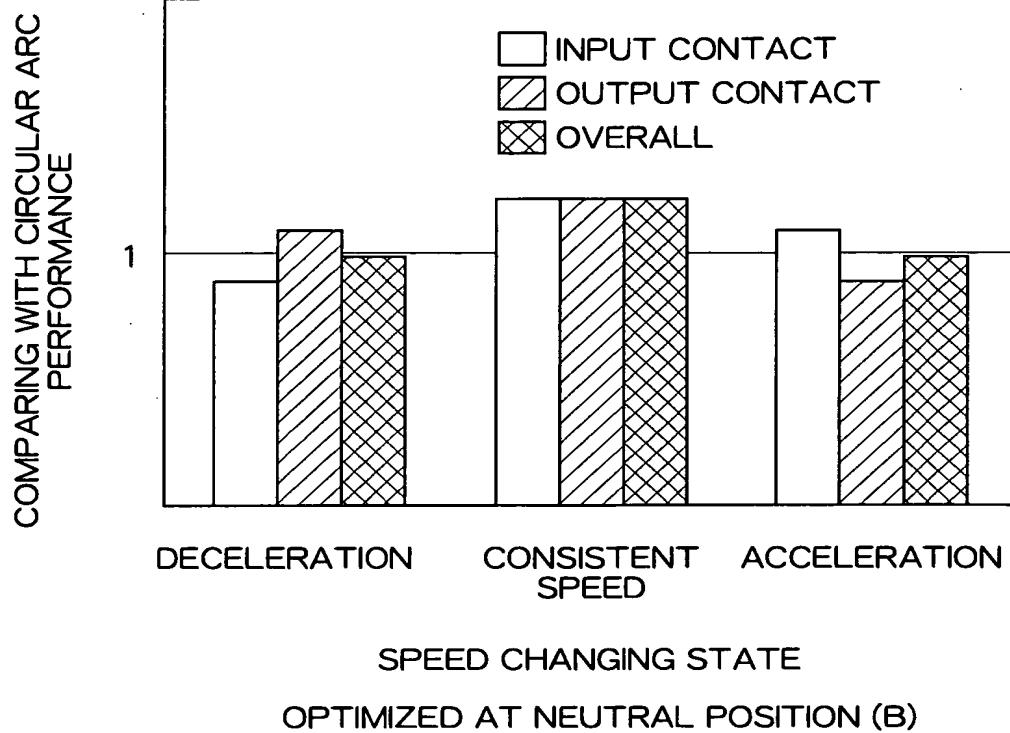


Fig.17

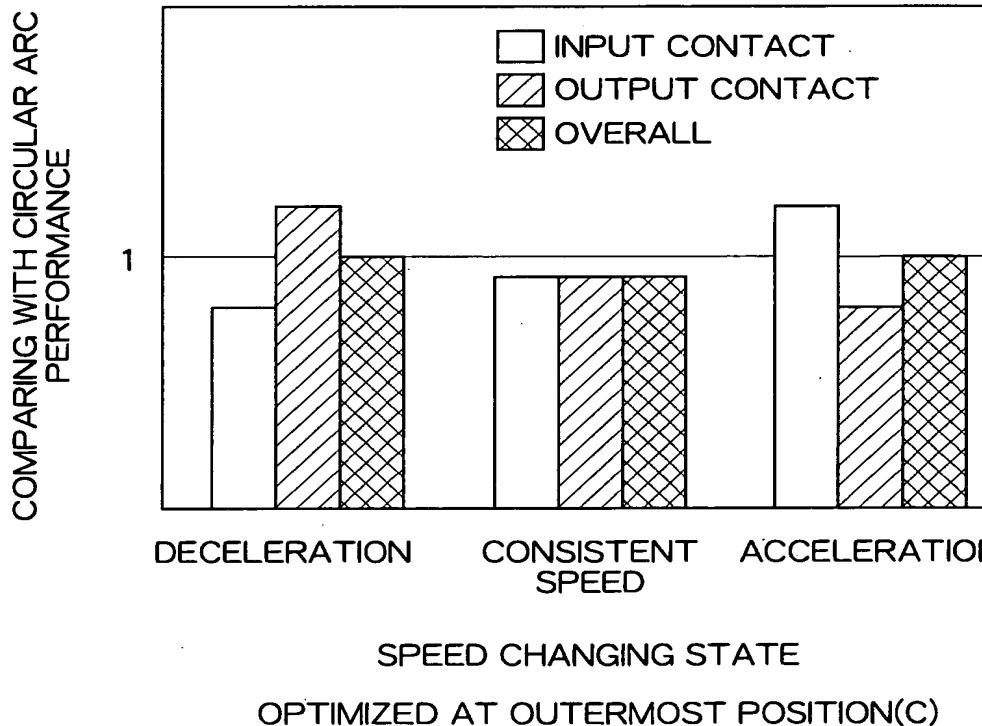


Fig.18

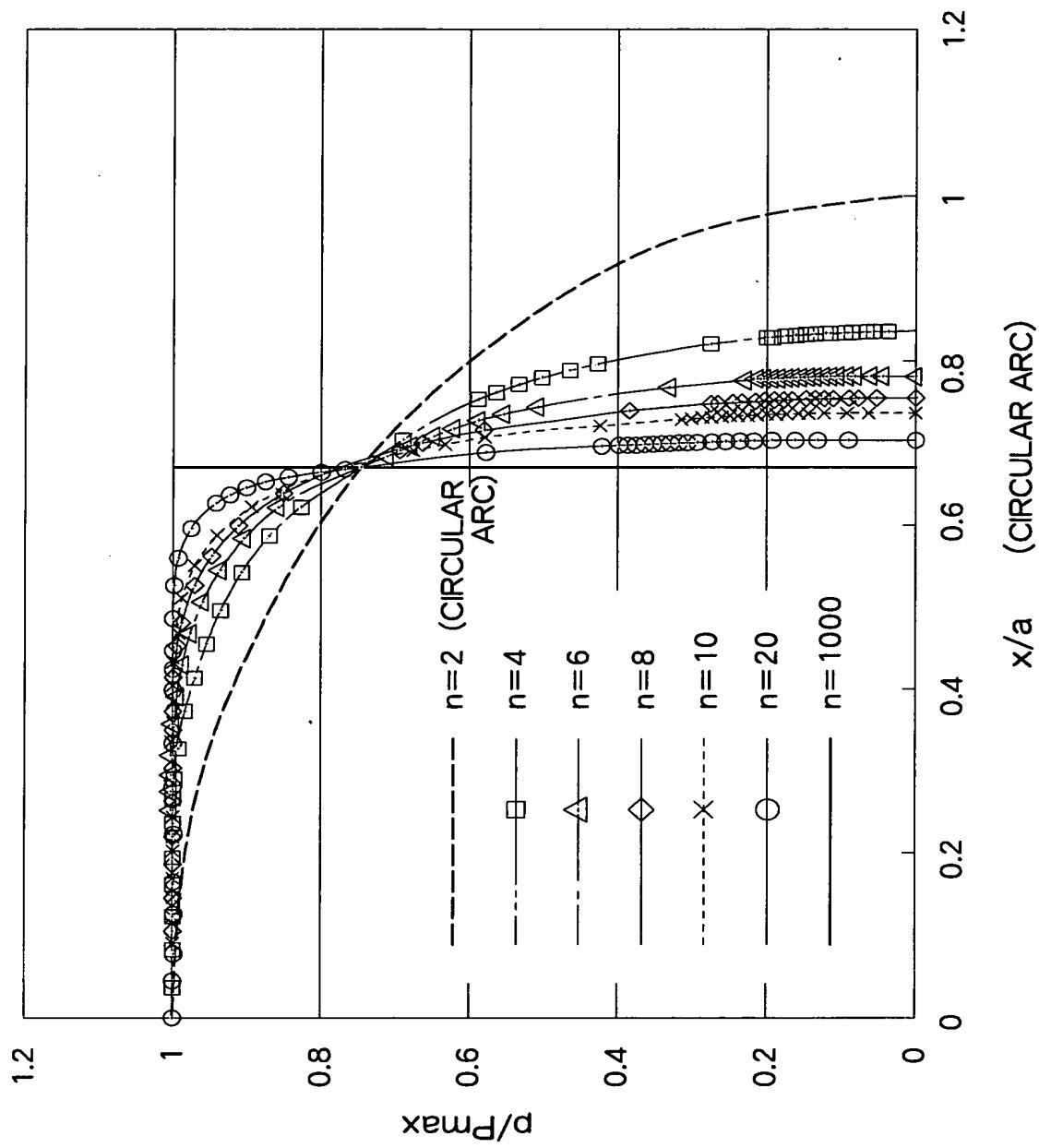


Fig. 19

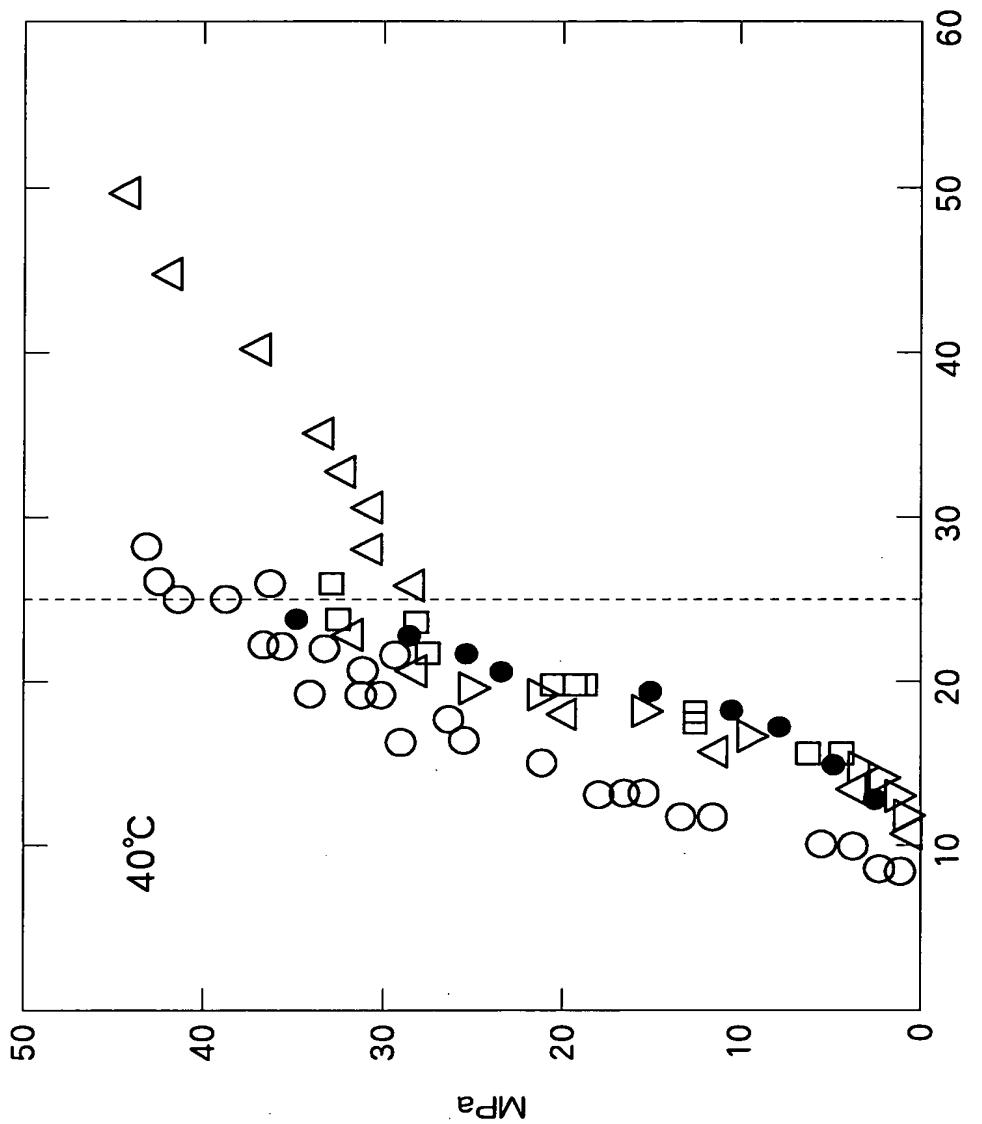


Fig.20

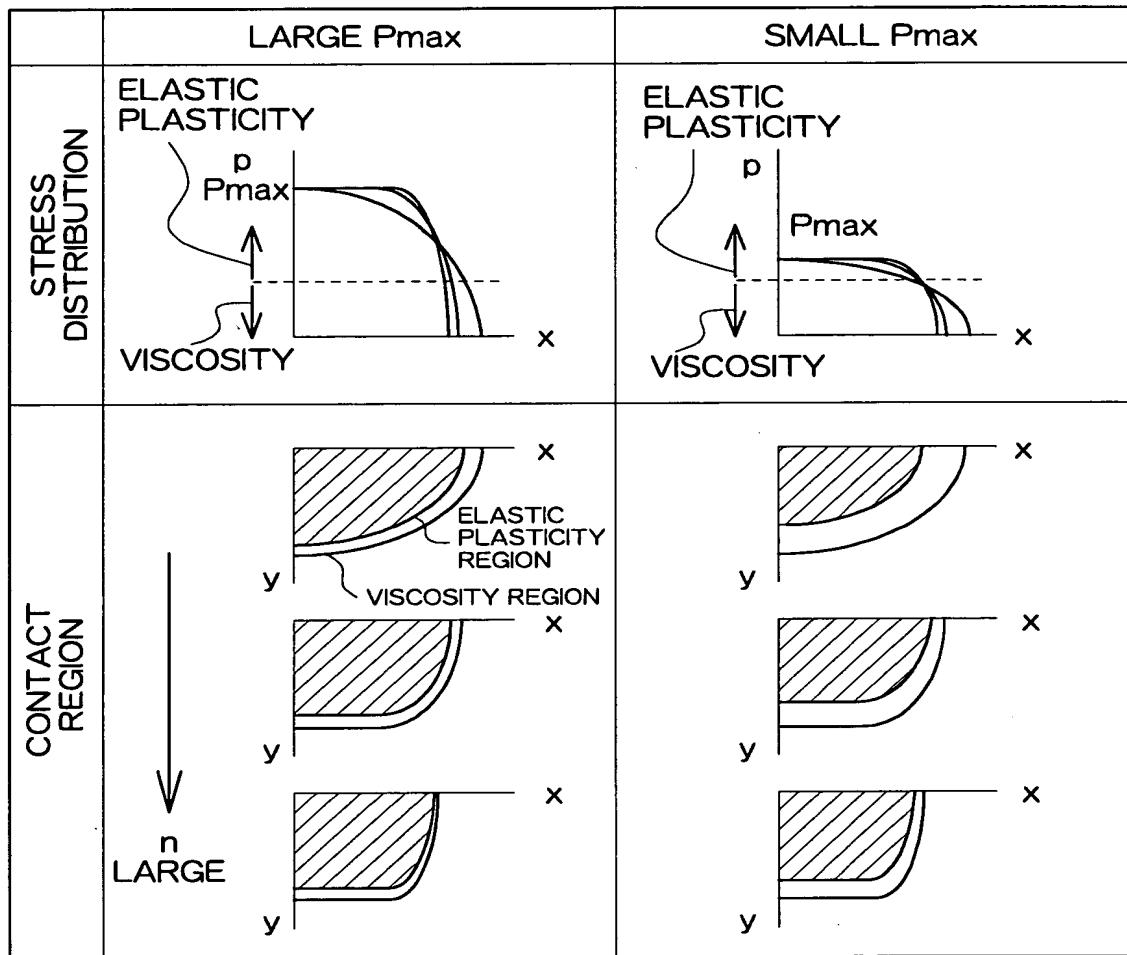


Fig.21

Ploss

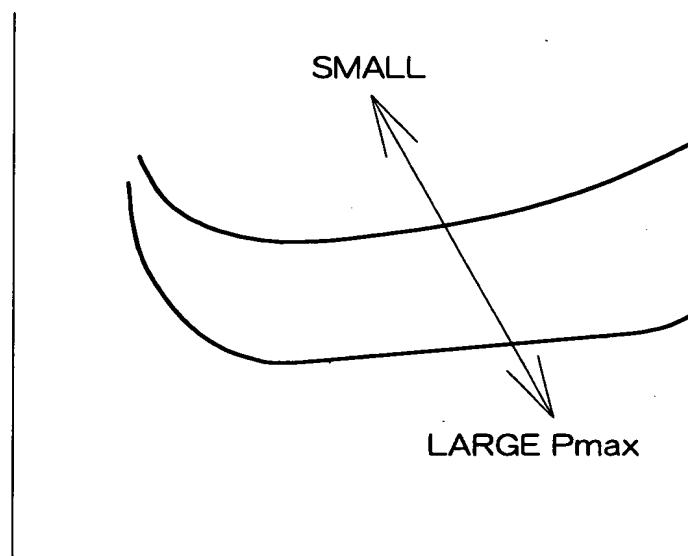


Fig.22

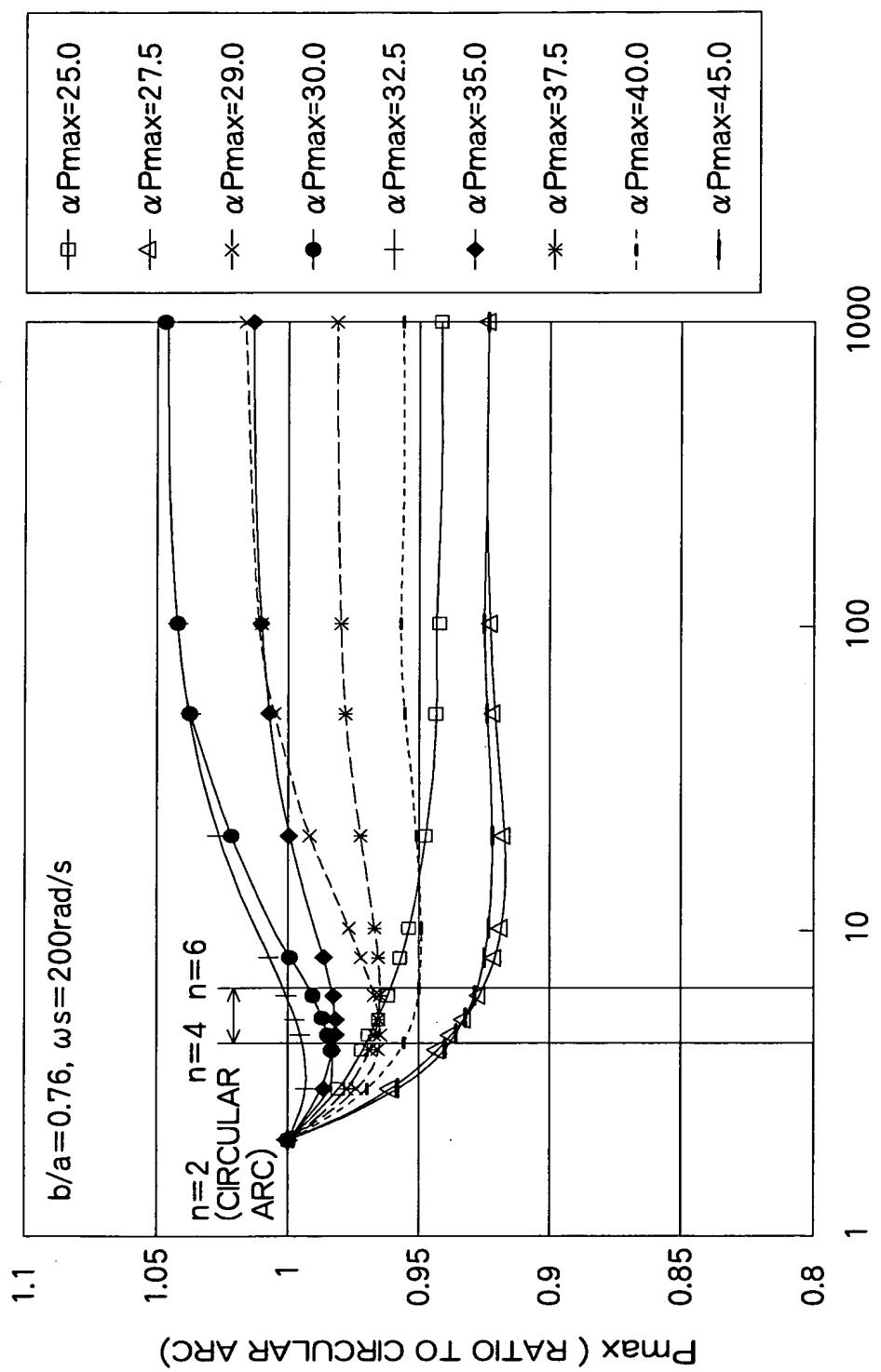


Fig.23

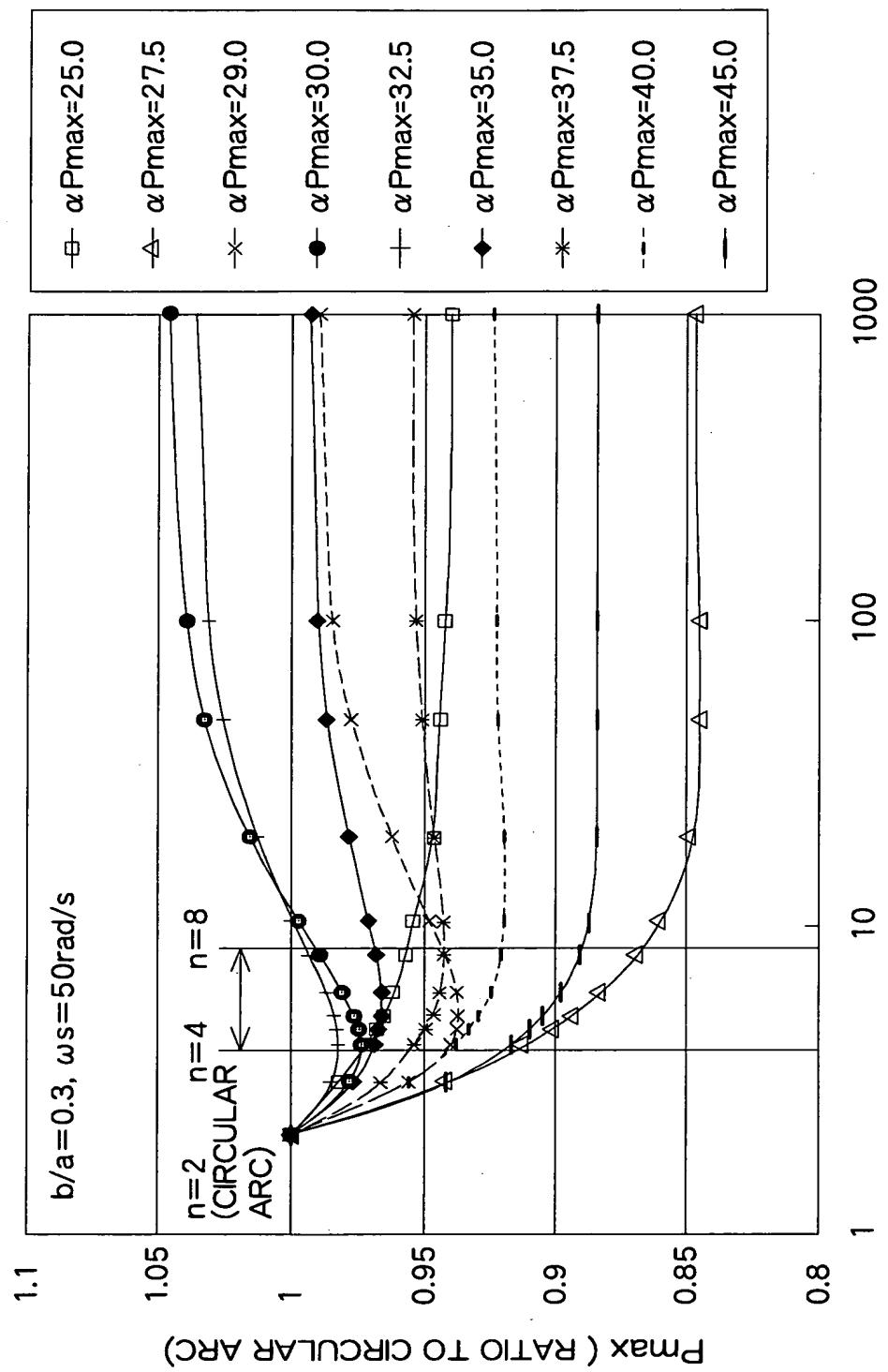


Fig.24

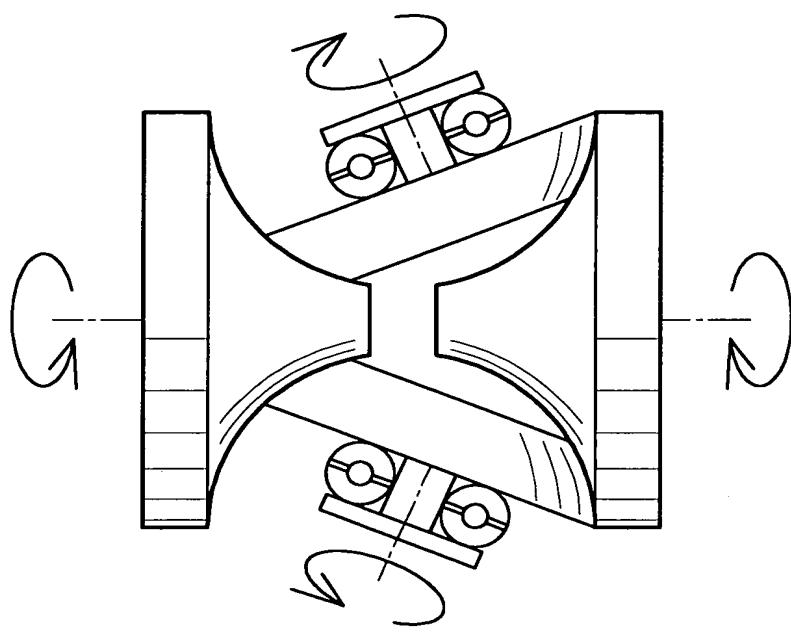


Fig.25

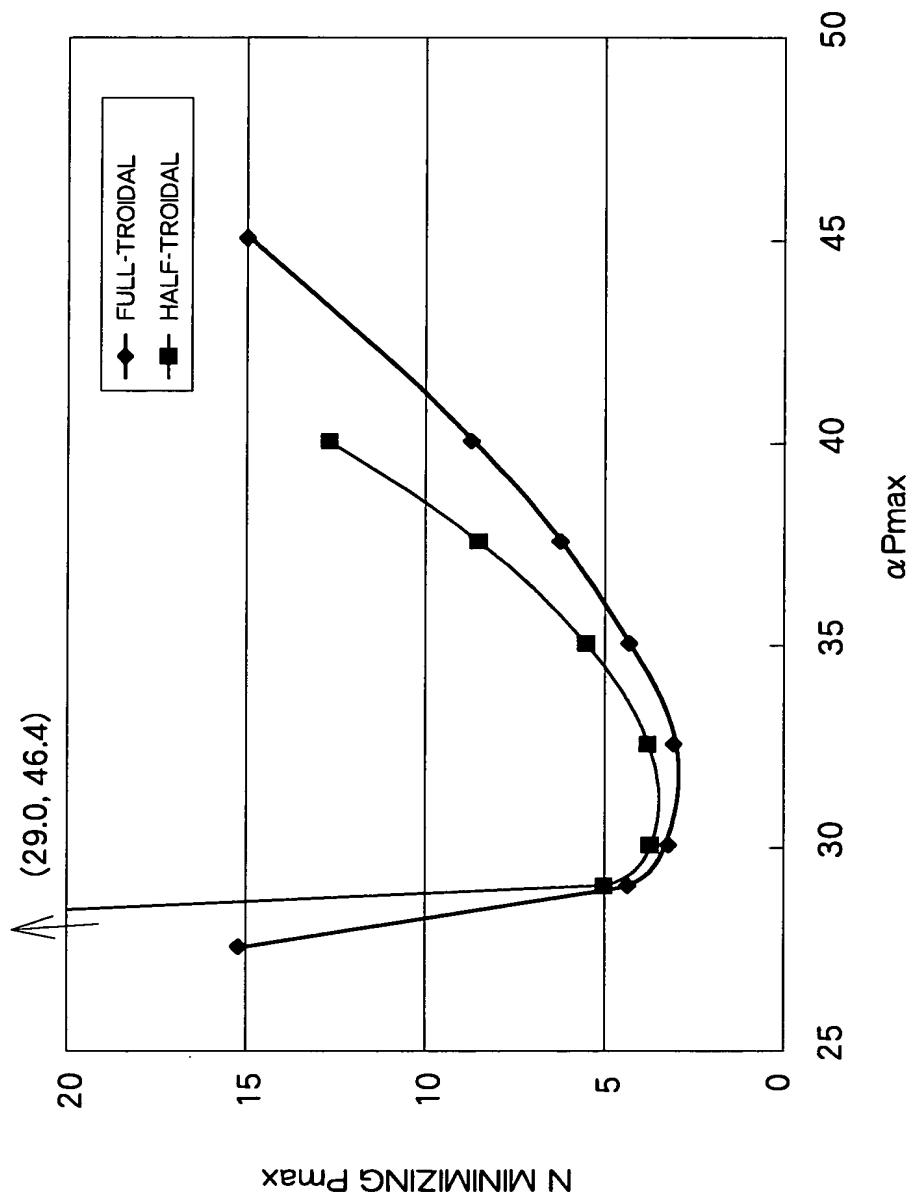


Fig.26

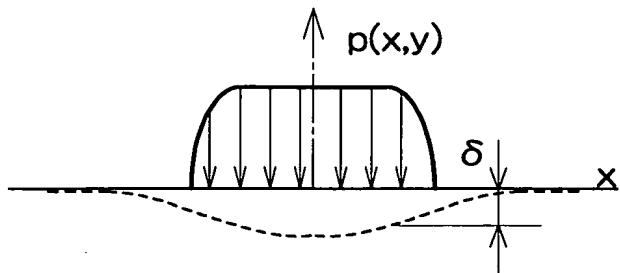
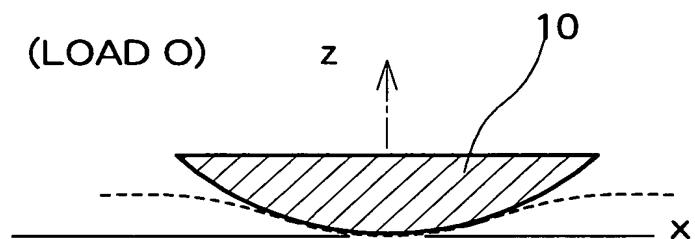


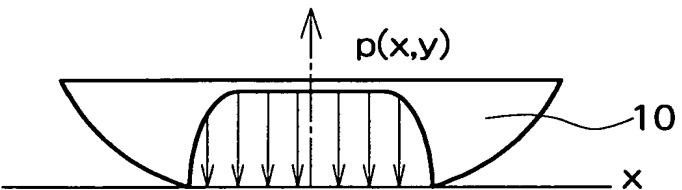
Fig.27A



16

Fig.27B

(LOAD W)



16

Fig.27C

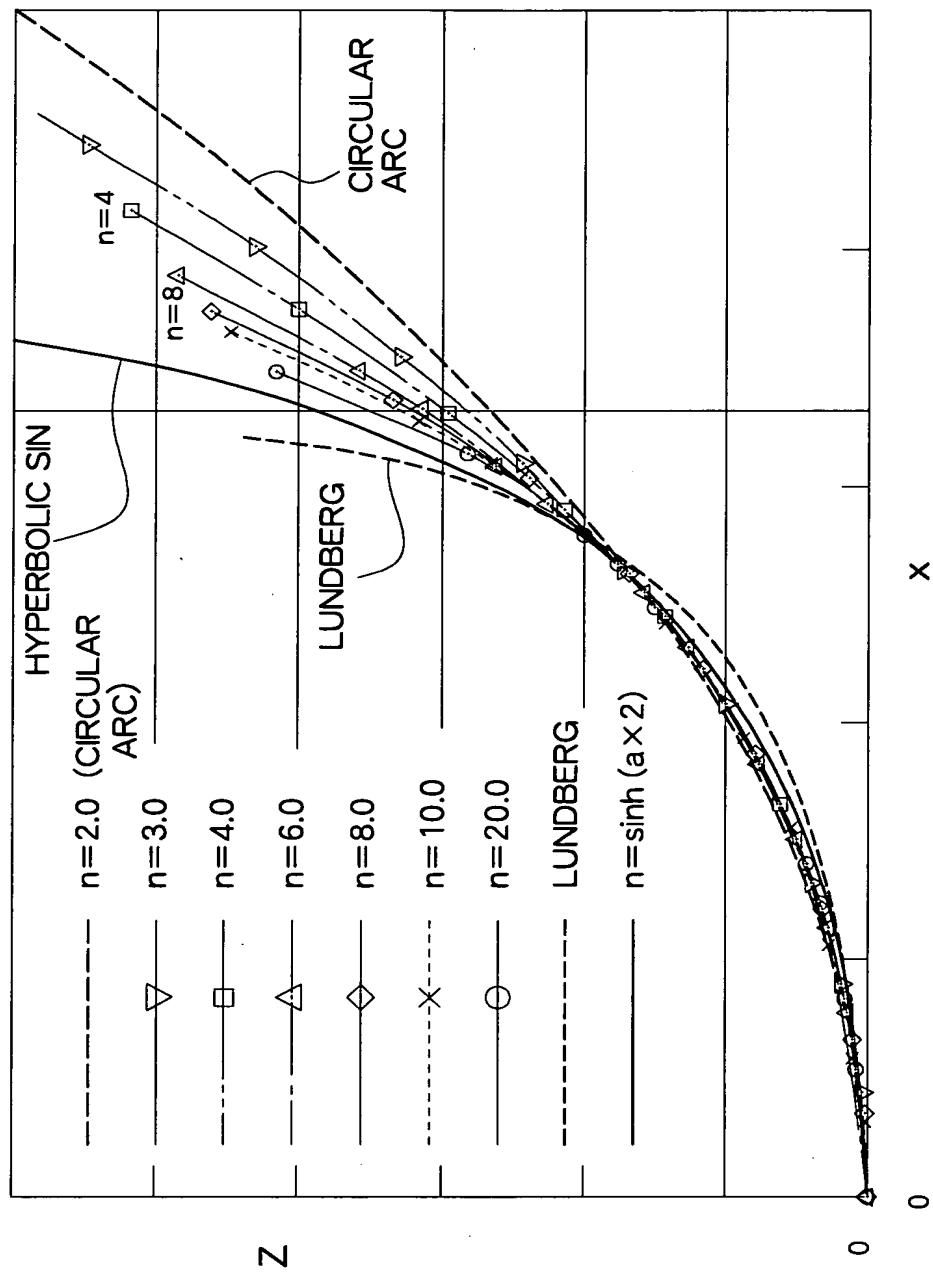


Fig.28